

Time-delay inteferometry for LISA: The algebraic approach

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Plan of Talk

- Introduction: LISA
- Laser frequency noise cancellation problem
- The TDI problem for LISA: 1st, modified 1st and 2nd generation TDI
- Mathematical structure: module of syzygies
- Complete solution for first generation TDI: static LISA in flat spacetime
- General relativistic model of LISA: flexing arms
- Using symmetries to simplify 2nd generation TDI
- Effect on TDI variables: Residual noise in modified first generation TDI
- 2nd generation TDI solutions for LISA with one arm dysfunctional

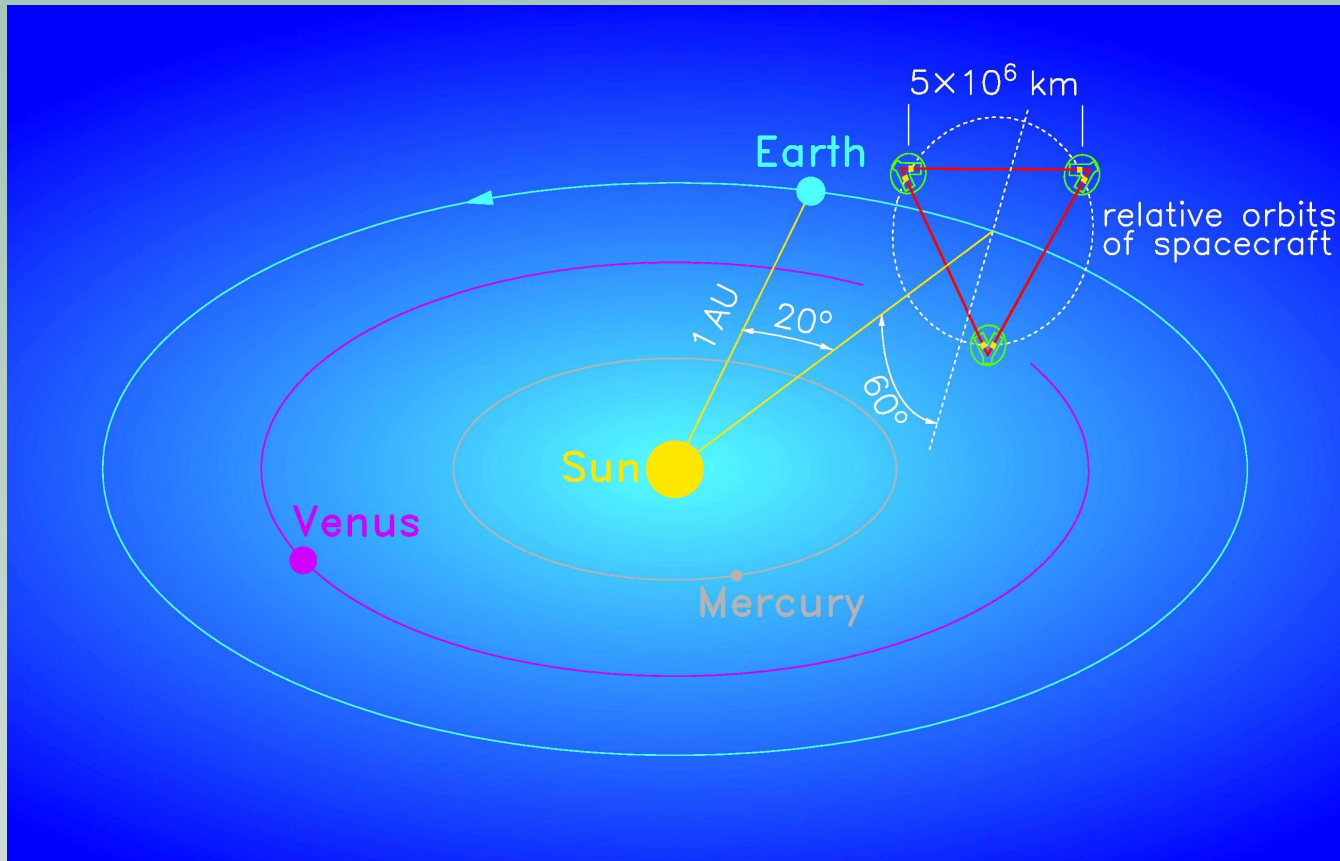


Introduction: LISA

- Ground-based Laser Interferometric Detector Network:
LIGO, VIRGO, TAMA, GEO & AIGO - 10 Hz to KHz.
- Ground-based gravitational wave detectors are close to acquiring astrophysically interesting data - LIGO entering the advanced detector stage
- The Space Antenna LISA: Why go to Space?
 - Low frequency searches : 10^{-5} Hz to 10^{-1} Hz
Complementary to groundbased detectors - just as the different astronomies, optical, radio, etc. complement each other.
 - Guaranteed Gravitational Wave Sources
- The LISA Project: ESA & NASA

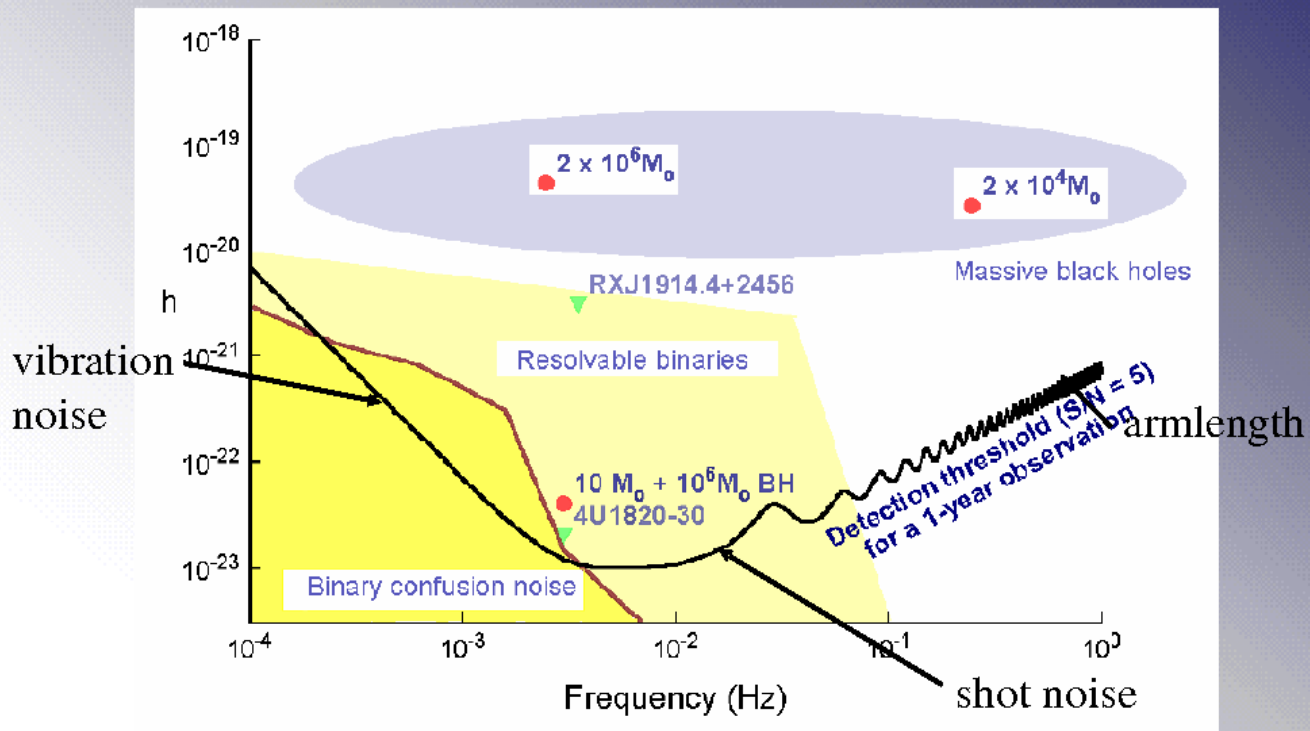


The LISA Project





LISA noise curve





Laser Frequency Noise

- Frequency of Laser: $\nu_0 \sim 3 \times 10^{14}$ Hz
- Frequency noise: $\widetilde{\Delta\nu} \sim 10 \text{ Hz} / \sqrt{\text{Hz}}$
- $h_{noise} = C(t) \equiv \frac{\Delta\nu(t)}{\nu_0} \sim 3 \times 10^{-14}$
- But $h_{sens} \sim 10^{-21}, 10^{-22}$
- **7 or 8 orders of magnitude**



Cancelling laser frequency noise in an unequal arm Interferometer

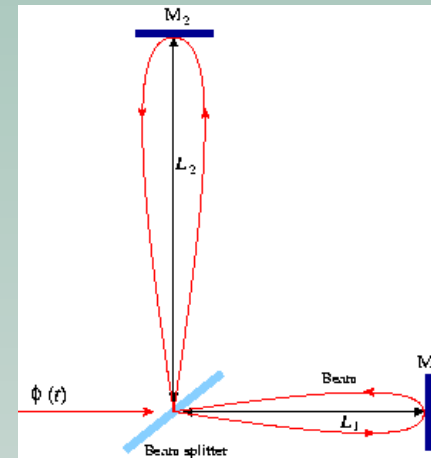
Equal arms: This noise is automatically cancelled

$C(t)$: Laser frequency noise

$$C_1(t) = C(t - 2L_1) - C(t) = (\mathcal{D}_1^2 - 1)C(t)$$

$$C_2(t) = C(t - 2L_2) - C(t) = (\mathcal{D}_2^2 - 1)C(t)$$

$$\Delta C(t) = C_1(t) - C_2(t) \neq 0$$



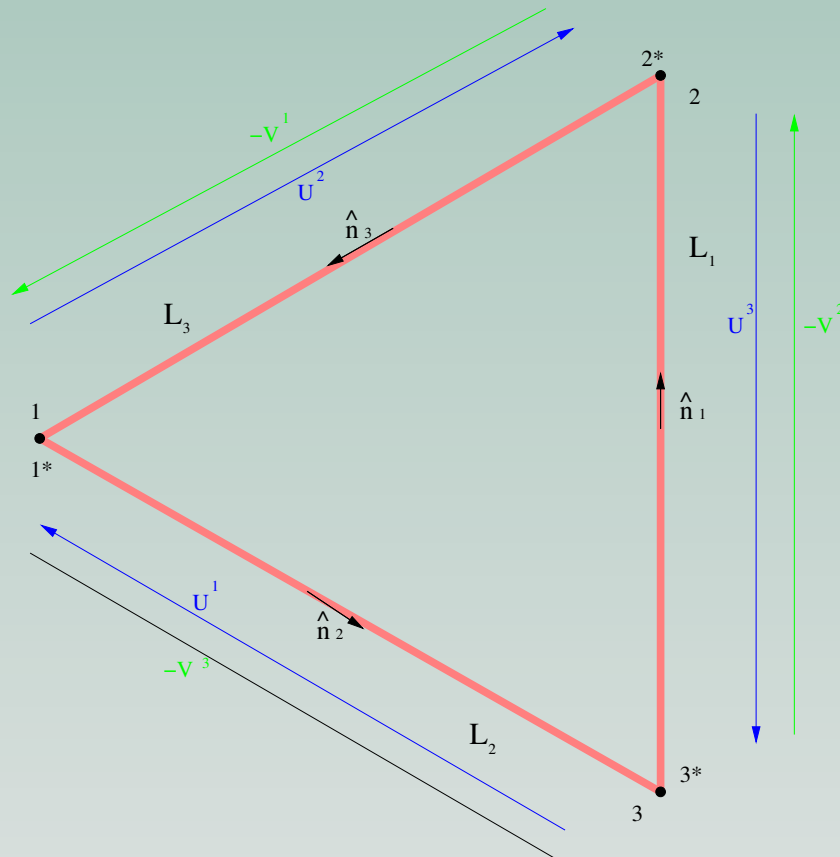
$$\begin{aligned} X(t) &= [C_1(t - 2L_2) - C_1(t)] - [C_2(t - 2L_1) - C_2(t)] \\ &= [(\mathcal{D}_2^2 - 1)(\mathcal{D}_1^2 - 1) - (\mathcal{D}_1^2 - 1)(\mathcal{D}_2^2 - 1)]C(t) \\ &= 0 \end{aligned}$$

Just LCM! Commutative algebra! Equal pathlengths



Schematic LISA

LISA: Interferometric triangle with unequal arms



- All L_i unequal
- $L_i \sim 5 \times 10^6 \text{ km} \sim 17 \text{ sec.}$
- Six elementary data streams:

$$U^1, U^2, U^3, V^1, V^2, V^3$$

- Example:

$$U^1 : 3 \longrightarrow 1$$

$$-V^1 : 2 \longrightarrow 1$$



The six elementary data streams

In LISA the data are recorded as fractional Doppler shifts

Three laser frequency noises: $C_i(t) = \frac{\Delta\nu_i(t)}{\nu_0}$

For example: $U^1(t) = C_3(t - L_2(t)) - C_1(t) + U_{\text{GW}}^1 + U_{\text{opt}}^1 + U_{\text{pf}}^1$

Algebra of finite difference operators $x, y, z; l, m, n$

$x : 1 \longrightarrow 2, l : 2 \longrightarrow 1, \dots$ + cyclic permutations

Displaying only the laser frequency terms: $U^1(t) = zC_3(t) - C_1(t) + \dots$

$$U^1 = zC_3 - C_1 + \dots$$

$$U^2 = xC_1 - C_2 + \dots$$

$$U^3 = yC_2 - C_3 + \dots$$

$$V^1 = C_1 - lC_2 + \dots$$

$$V^2 = C_2 - mC_3 + \dots$$

$$V^3 = C_3 - nC_1 + \dots$$



The General TDI for LISA

A general data combination:

$$X = \sum_{i=1}^3 p_i V^i + q_i U^i$$

where p_i and q_i are the polynomials in x, y, z, l, m, n operators which in general do not commute.

Laser frequency noise terms should vanish for arbitrary C_i if:

$$\begin{aligned} p_1 - q_1 + q_2 x - p_3 n &= 0 \\ p_2 - q_2 + q_3 y - p_1 l &= 0 \\ p_3 - q_3 + q_1 z - p_2 m &= 0 \end{aligned}$$

Solutions: Polynomial vectors: **module of syzygies**



The solution space: A module

Eliminate p_1 and p_2 by Gaussian elimination:

$$\psi(x, y, z; l, m, n) \equiv p_3(1 - nlm) + q_1(z - lm) + q_2(xl - 1)m + q_3(ym - 1) = 0$$

$\mathcal{Q}(x, y, z, l, m, n) \equiv \mathcal{K}$ is in general non-commutative polynomial ring.

Consider the map $\varphi : \mathcal{K}^4 \longrightarrow \mathcal{K}$ which takes the polynomial vector $(p_3, q_1, q_2, q_3) \in \mathcal{K}^4$ to $\psi(x, y, z, l, m, n) \in \mathcal{K}$.

φ is a homomorphism of modules and its **kernel** $\varphi^{-1}(0)$ is essentially the submodule we want.

φ can be easily extended to \mathcal{K}^6 via the elimination equations and then the kernel of this homomorphism is the module $\mathcal{M} \subset \mathcal{K}^6$.



Ist and IInd generation TDI

- **Stationary LISA in flat spacetime: Ist generation TDI**

$x = l, y = m, z = n$ - Operators commute

- TDI needs to be generalised taking into consideration, moving LISA, changing armlengths, gravitational field: A **general relativistic** model of LISA optical links is required to account for Sagnac effect, changing armlengths, gravitational field - Shapiro delay, etc.

- **Sagnac Effect - Modified Ist generation TDI**

Light travel times in two directions around the Sagnac circuit are different:

$$L_i \neq L'_i, \Delta(L_1 + L_2 + L_3) \sim 4A\omega/c \sim 28 \text{ km}$$

Armlengths constant in time, but x, y, z, l, m, n all different - **Operators commute**

- **Time dependent armlengths - IInd generation TDI**

$$\dot{L}_i \lesssim 10 \text{ m/sec.}$$

$$\phi(t - L_1 - L_2(t - L_1)) \neq \phi(t - L_2 - L_1(t - L_2))$$

For example: $xy \neq yx$ - **Operators do not commute**



Complete solution for 1st generation TDI

Some simple examples found by Estabrook, Tinto, Armstrong, JPL, Pasadena, U.S.
- adhoc methods used (1999 - 2001).

Symmetric Sagnac:

$$\zeta = yV^1 + zV^2 + xV^3 + yU^1 + zU^2 + xU^3$$

$$yC_1 - xyC_2 + zC_2 - yzC_3 + xC_3 - zxC_1 + yzC_3 - yC_1 + zxC_1 - zC_2 + xyC_2 - xC_3 = 0$$

This is an identity!

Polynomial vectors in the delay operators:

$$\zeta = (y, z, x, y, z, x)$$

$$X = (1 - z^2, 0, z(x^2 - 1), 1 - x^2, x(z^2 - 1), 0)$$

X: Michelson - Sensitivity curve of LISA

General method to generate **ALL** 1st generation TDI



The General Method

Gaussian elimination of p_1, p_2 leads to one equation,

$$(xyz - 1)p_3 + (xy - z)q_1 + y(1 - x^2)q_2 + (1 - y^2)q_3 = 0$$

- Solutions are 4-tuples: polynomial vectors $\{p_3, q_1, q_2, q_3\}$
- Kernel of a module homomorphism
- Solution space: **Module** - *first module of syzygies*.
- Resubstitution of p_1 and p_2 - (isomorphic) module of 6-tuple polynomial vectors $\{p_1, p_2, p_3, q_1, q_2, q_3\}$



Rings and Modules

- Commutative rings with identity - **No multiplicative inverse**
- Module: **Abelian group over a ring**
- Ideals: U an ideal in a ring R , $u \in U$, $r \in R$ then $ru \in U$
- Polynomial rings: $Q[x]$, $Q[x, y, z]$
- Principal ideals, PIDs, ***greatest common divisor*** - gcd
- Gröbner basis: **Generalisation of the gcd in a PID**



Generating the Module of Syzygies

- Obtain a Gröbner basis for the ideal generated by the coefficients:
 - $xyz - 1, xy - z, y(1 - x^2), 1 - y^2$
 - Gröbner basis: $\{x^2 - 1, z^2 - 1, y - xz\}$
- Gröbner basis to module:
 - Form matrices connecting Gröbner basis to the coefficients and vice-versa, and then the generators of the module are given in terms of the matrices
 - The theorems guarantee that the full module is generated - independent of the order chosen

The above procedure generates the 4-tuple polynomial generators

The polynomial six tuples $\{p_1, p_2, p_3, q_1, q_2, q_3\}$ can be obtained from the elimination equations.



Obtaining the generators of the module

Coefficients: $f_1 = xyz - 1$, $f_2 = xz - y$, $f_3 = x(1 - z^2)$, $f_4 = 1 - x^2$ **A**
Gröbner basis for the ideal $U = \{f_1, f_2, f_3, f_4\}$ is:

$$\mathcal{G} = \{g_1 = z^2 - 1, g_2 = y^2 - 1, g_3 = x - yz\}$$

Write: $f_i = d_{ij}g_j$ and $g_j = c_{ji}f_i$, then,

$$d = \begin{pmatrix} 1 & z^2 & yz \\ y & 0 & z \\ -x & 0 & 0 \\ -1 & -z^2 & -(x + yz) \end{pmatrix}, \quad c = \begin{pmatrix} 0 & 0 & -x & z^2 - 1 \\ 1 & -y & 0 & 0 \\ 0 & z & 1 & 0 \end{pmatrix} \quad (1)$$

Rows of $d.c$ are one set of generators: **A**

S-polynomials: Write the S-polynomials in terms of the Gröbner basis \longrightarrow **b**

Rows of $b.c$ are the remaining set of generators **B^***

Full set: **$A \cup B^*$** : 7 generators but not independent



Generators of the Module of Syzygies

Using the software Macaulay 2, we obtain one generating set:

$$X^{(1)} = (yx - z, 0, x^2 - 1, 0, zx - y, x^2 - 1)$$

$$X^{(2)} = (y, z, x, y, z, x)$$

$$X^{(3)} = (1, x, yx, 1, yz, z)$$

$$X^{(4)} = (yz, 1, y, x, 1, zx)$$

Another generating set:

$$\alpha = (1, x, yx, 1, yz, z)$$

$$\beta = (yz, 1, y, x, 1, zx)$$

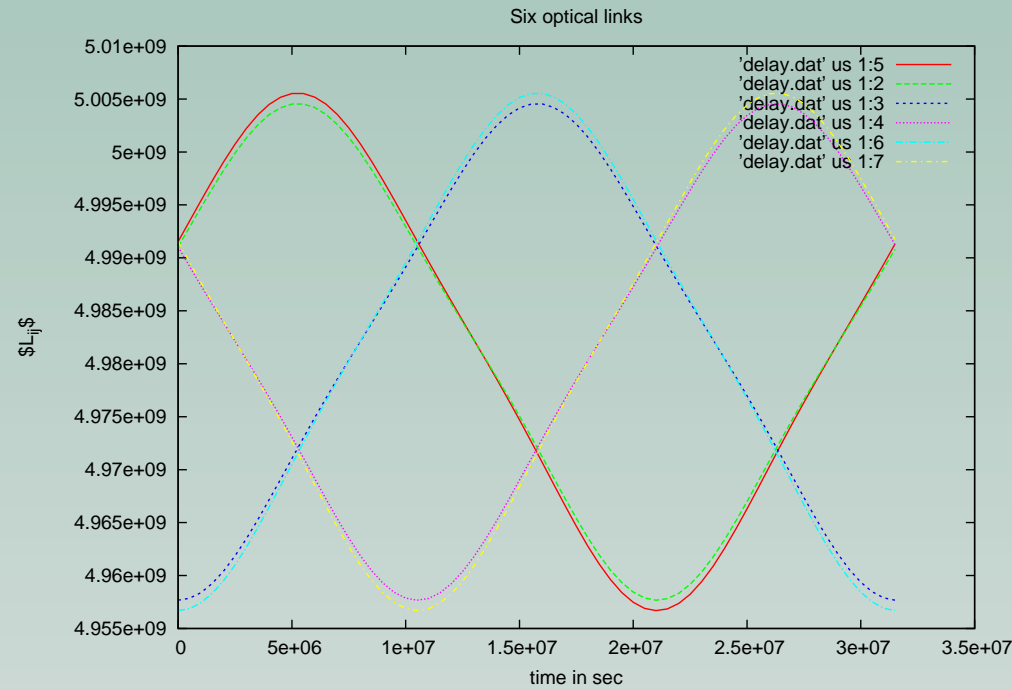
$$\gamma = (z, zx, 1, yx, y, 1)$$

$$\zeta = (y, z, x, y, z, x)$$

Module is independent of the order chosen for computing the Gröbner basis



Minimal flexing model in Sun's field



Choice of spacecraft orbits: Variation in armlength $\sim 48,000$ km and $\dot{L} \lesssim 4$ m/sec



Including the Earth: The CW Frame

Transformations to Clohessy-Wiltshire (CW) frame:

$$\begin{aligned}x &= (X - R \cos \Omega t) \cos \Omega t + (Y - R \sin \Omega t) \sin \Omega t \\y &= -(X - R \cos \Omega t) \sin \Omega t + (Y - R \sin \Omega t) \cos \Omega t \\z &= Z\end{aligned}\tag{2}$$

Coordinates of Earth in CW frame: $(x_{\oplus}, y_{\oplus}, 0)$ are constant

$$x_{\oplus} = 9.0 \times 10^6 \text{ km}$$

$$y_{\oplus} = 51.3 \times 10^6 \text{ km}$$



The perturbation by the Earth

Dhurandhar, Vinet, Nayak (2008)

Perturbed CW equations:

$$\begin{aligned}\ddot{x} - 2\Omega\dot{y} - 3\Omega^2x + \epsilon\Omega^2(x - x_{\oplus}) &= 0, \\ \ddot{y} + 2\Omega\dot{x} + \epsilon\Omega^2(y - y_{\oplus}) &= 0, \\ \ddot{z} + \Omega^2(1 + \epsilon)z &= 0\end{aligned}$$

Ratio of tidal forces of Earth to Sun: $\epsilon \simeq 7.16 \times 10^{-5}$

$\epsilon_{\text{Jupiter}}/\epsilon_{\text{Earth}} \sim 0.09$

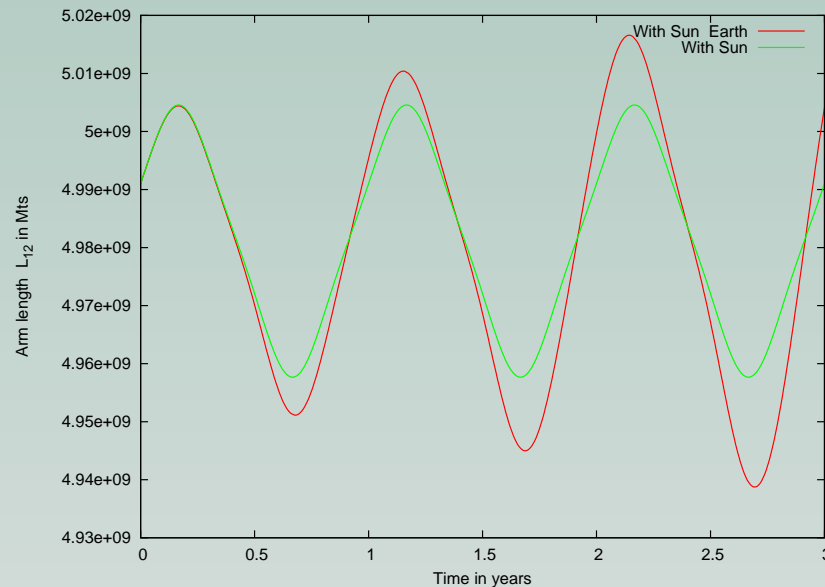
$\epsilon_{\text{Moon}}/\epsilon_{\text{Earth}} \sim 0.01$



l_{12} in Sun's and Sun + Earth's field

Earth's perturbative effect superposed on the Keplerian S/C orbits:

This is done by going to the CW frame, taking a zero'th order solution and perturbing it by the Earth's tidal field

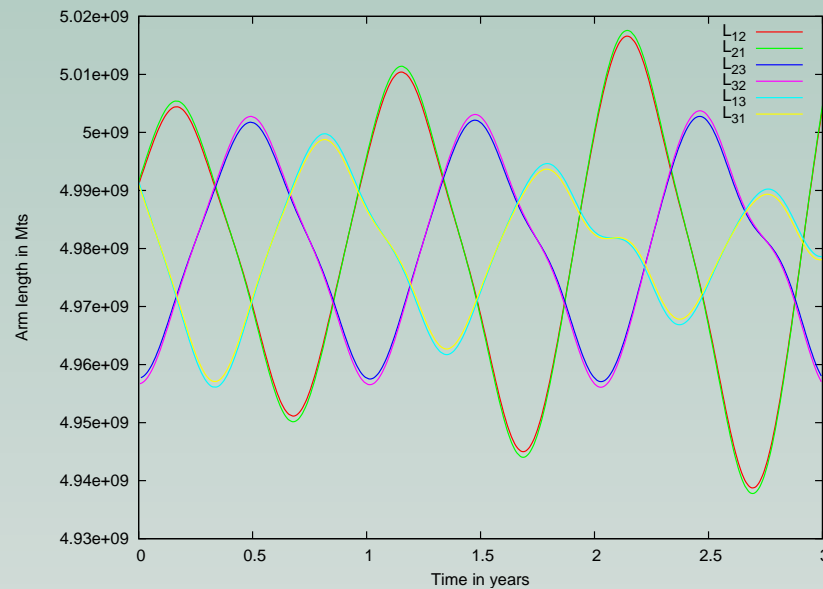


In year 3: Peak increase of $\sim 20,000$ km



Optical links: General Relativistic Treatment

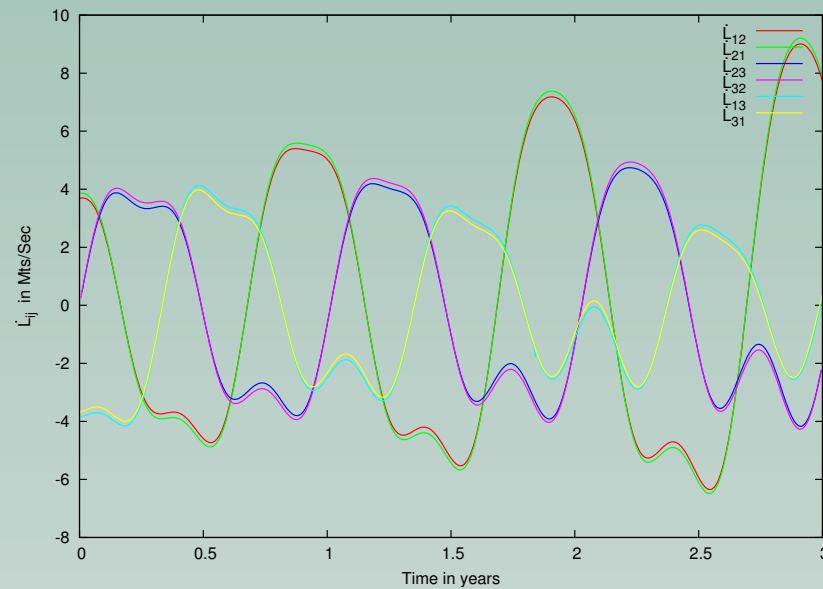
- Optical links are obtained by numerically integrating the null geodesics in the Schwarzschild metric determined by Sun's mass.
- Fortan 90 code



Peak to peak variation in the 3rd year $\sim 80,000$ km.



The \dot{L}_{ij}



Year 3: $\dot{L}_{ij} \lesssim 8$ m/sec.

$$|\dot{L}_x - \dot{L}_l| \sim 0.1 \text{ m/sec}, \quad \frac{1}{c^2} [x, l] \dot{C} \simeq \Delta t \dot{C} = \Delta C$$

$S_{\Delta C}(f = 1 \text{ mHz}) \sim 10^{-48} \text{ Hz}^{-1} \longrightarrow x, l \text{ commute! Approximate symmetry!}$



Approximate symmetries

We drop $\ddot{L} \sim 10^{-6}$ m/sec² and $\dot{L}^2 \sim 10^{-15}$ terms:

$$(jk - kj)C(t) = (L_j \dot{L}_k - L_k \dot{L}_j) \dot{C}(t - L_j - L_k)$$

Since $\dot{L}_x \simeq \dot{L}_l \longrightarrow [x, l] \simeq 0$.

Similarly, $[y, m] \simeq 0$, $[z, n] \simeq 0$.

In fact, if $y_1 y_2 \dots y_n$ is a permutation of $x_1 x_2 \dots x_n$, where x_k is any of the operators, then,

$$[x_1 x_2 \dots x_n, y_1 y_2 \dots y_n] \simeq 0, \quad n \geq 2$$

For example:

$$[xy, yx] = xy yx - yx xy = xy^2 x - yx^2 y \simeq 0$$



The quotient ring $\bar{\mathcal{K}}$

Construct the ideal $\mathcal{U} \subset \mathcal{K}$ as follows:

- Use the above nearly vanishing commutators to generate the ideal \mathcal{U} - consider all linear combinations of the commutators.
- Form the quotient ring $\bar{\mathcal{K}} \equiv \mathcal{K}/\mathcal{U}$ - any element of $\bar{p} \in \bar{\mathcal{K}}$ is of the form $\bar{p} = p + \mathcal{U}$, where $p \in \mathcal{K}$ - it is an equivalence class of polynomials in \mathcal{K} .
- The new module is now over the quotient ring \bar{K} with each element written as $(\bar{p}_i, \bar{q}_i) \in \bar{\mathcal{K}}^6$

Effectively, there are now less polynomials in \bar{K} than in \mathcal{K} and hence the original ring is simplified; eg. $\bar{l}\bar{x} = \bar{x}\bar{l}$, $\bar{x}\bar{y}^2\bar{x} = \bar{y}\bar{x}^2\bar{y}$, etc.



Residual Noises in Modified 1st generation TDI

Example of Sagnac α :

$$\alpha = (\kappa, \kappa l, \kappa l m; \eta, \eta z y, \eta z) \quad \kappa = 1 - z y x, \eta = 1 - l m n$$

$$S_C(f) = \langle |\tilde{C}(f)|^2 \rangle \sim 10^{-27} \text{ Hz}^{-1}$$

$$\Delta C = \alpha_1 C_1 + \alpha_2 C_2 + \alpha_3 C_3$$

$\alpha_1 = [z y x, l m n]$, $\alpha_2 = \alpha_3 = 0$: Upto first order in \dot{L} and dropping \ddot{L} terms and higher order:

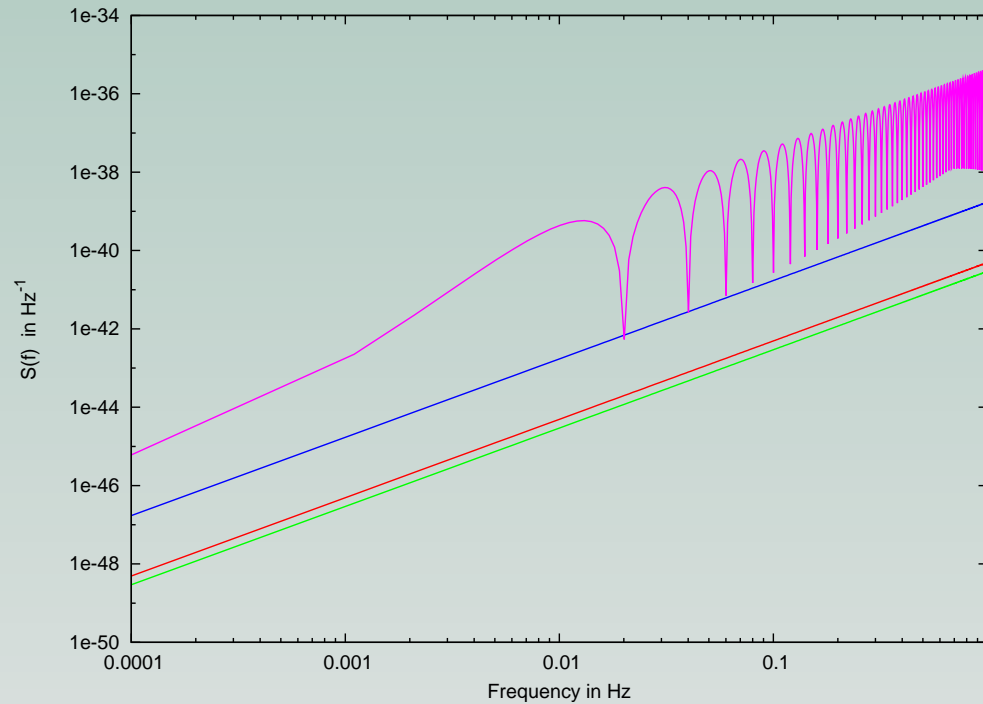
$$\Delta t(t) = \frac{1}{c^2} [(L_x + L_y + L_z)(\dot{L}_l + \dot{L}_m + \dot{L}_n) - (L_l + L_m + L_n)(\dot{L}_x + \dot{L}_y + \dot{L}_z)]$$



Sagnac

$$S_{\Delta C}(f; t) = 4\pi^2 \Delta t(t)^2 f^2 S_C(f)$$

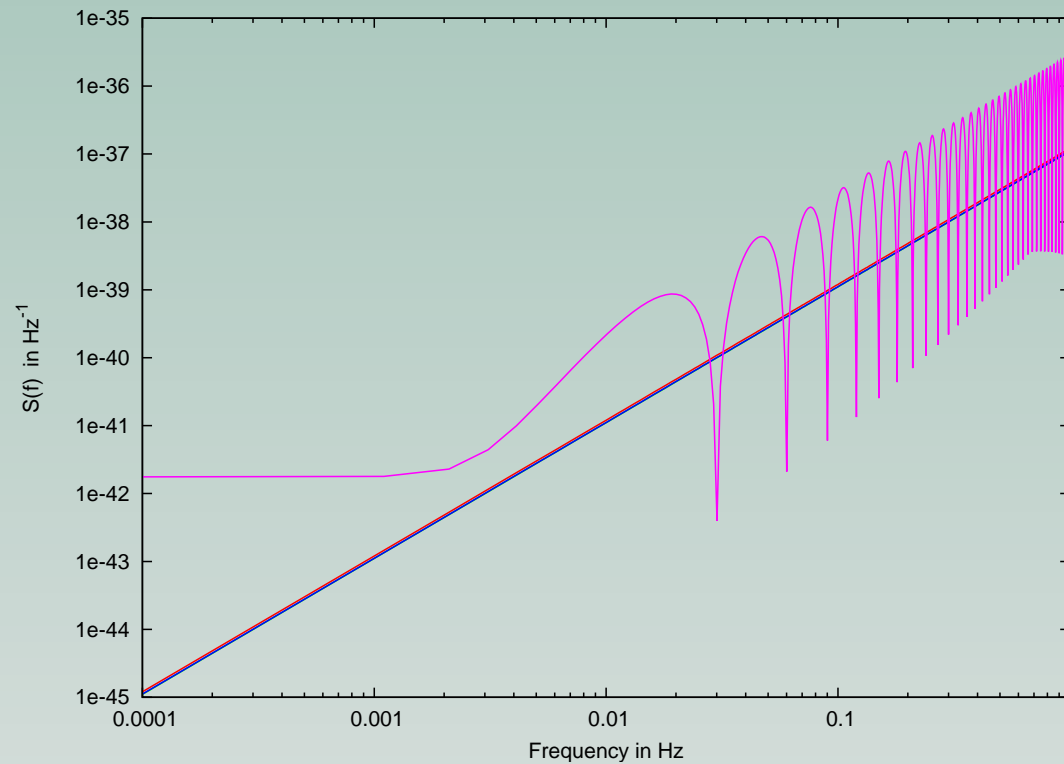
Also the secondary noise PSD must be multiplied by $4 \sin^2(3\pi f L_0)$ because of κ, η





TDI variable: Michelson

$$X = (1 - zn, 0, (lx - 1)z; 1 - lx, (zn - 1)l, 0)$$

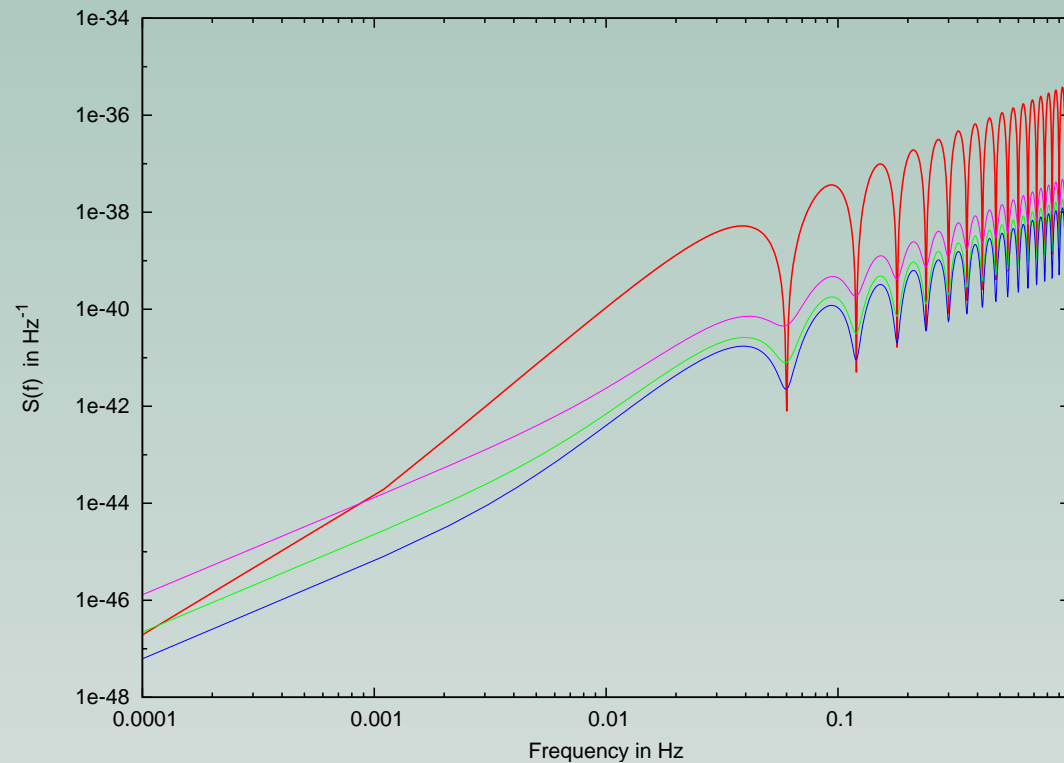


Residual noise about 10 – 20%.



TDI variable: ζ

$$\zeta_1 = (y(zx - m), (ln - y)z, (zx - m)l, m(ln - y), (ln - y)z, (zx - m)l)$$

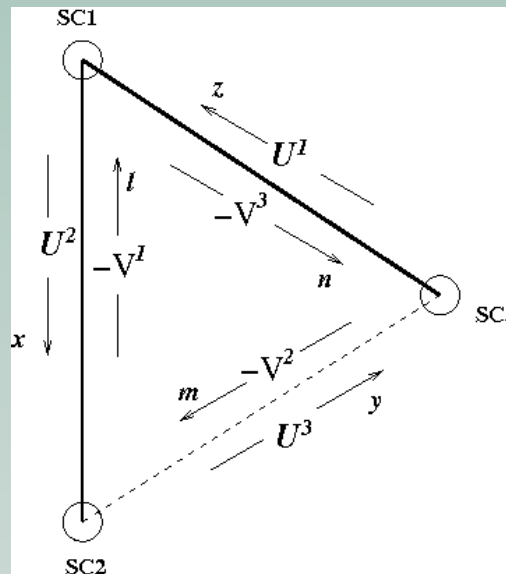


Residual noise suppressed except at low frequencies $\lesssim 1$ mHz.



IInd generation TDI for LISA: one arm dysfunctional

The general TDI problem extremely difficult: Special case when one of the arms is dysfunctional, say, connecting S/C 2 to S/C 3.



Links: x, l, z, n

Polynomials: $p_2 = q_3 = 0$

Reduced equations: $q_2 = -p_1 l, p_3 = -q_1 z$

Only one non-trivial equation: $p_1(1 - lx) - q_1(1 - zn) = 0$



The Michelson solution: round trip TDI operators

Round trip operators: $a = lx, b = zn$

Equation: $p_1(1 - a) - q_1(1 - b) = 0$

Michelson solution: $p_1 = 1 - b - ba + ab^2, q_1 = 1 - a - ab + ba^2$

Solution because $p_1(1 - a) - q_1(1 - b) \equiv \Delta = [ba, ab] \simeq 0$

Tinto, Armstrong, Estabrook, Vallisneri

Many more solutions possible of higher degrees

Construct commutators $\in \mathcal{U}$ of higher degrees: **To each such commutator there is a solution**



Higher degree solutions $n = 2$

Commutator $\Delta = [ab^2a, ba^2b] \simeq 0$

Solution with this commutator $[ab^2a, ba^2b]$:

$$p_1 = 1 - b - ba + ab^2 - ba^2b + ab^2ab + ab^2aba - ba^2bab^2$$

$$q_1 = 1 - a - ab + ba^2 - ab^2a + ba^2ba + ba^2bab - ab^2aba^2$$

Two other commutators: $[a^2b^2, b^2a^2], [abab, baba] \in \mathcal{U}$

These produce two other linearly independent solutions of degree 7 in a, b which is 14 in x, l, z, n .

p_3, q_2 are of degree 15.



Solutions of degree $n \geq 3$

First list the commutators in some order: Choose length lexicographical order
 $a < b$

$a < b < aa < ab < ba < bb < aaa < aab < aba < abb < baa < bab < bba < bbb < aaaa \dots$

A commutator must have equal numbers of a 's and b 's. List commutators by their **first** string.

$n = 3$: $aaabbb < aababb < aabbab < aabbba < abaabb \dots$ **10 such commutators.**

$n = 4$: Length of string 8 in a, b and **35 such commutators**

Mathematically: infinite family; **Physically restricted by \ddot{L} terms: $n \leq 10$.**



Summary

- Problem solved for 1st generation TDI.
- General relativistic model worked out numerically: **Level of 'non-commutativity' involved has been computed.**
- Look for an optimal model of LISA which minimises flexing and so that modified 1st generation TDI suffice.
- **OR** use symmetries to simplify the 11nd generation TDI problem - **problem not fully non-commutative** - thus simplify the polynomial ring by quotienting it with an ideal generated by near vanishing commutators.
- Family of solutions: **11nd generation TDI for the special case when LISA's one arm is dysfunctional.**